

Dual displacement motor A10VM Plug-in dual displacement motor A10VE

RE 91 703/09.99 1/16 Replaces: 08.98

open and closed circuit

Size 28...85 Series 5 Nominal pressure 280 bar Peak pressure 350 bar



A10VM A10VE

Contents

Ordering code / Standard range
Hydraulic fluid / Filtration / Installed position
Technical data
Direct control pressure DG
Hydraulic two-point control HZ
Electrical two-point control EZ.
Unit dimensions A10VM 28 DG, port plate 60
Unit dimensions A10VM 28 HZ, port plate 66
Unit dimensions A10VE 28 EZ, port plate 60
Unit dimensions A10VM 45 DG, port plate 64
Unit dimensions A10VM 45 EZ, port plate 64
Unit dimensions A10VM 45 EZ, port plate 60
unit dimensions A10VE 45 HZ, port plate 66
Unit dimensions A10VM 63 EZ, port plate 60
Unit dimensions A10VE 63 EZ, port plate 60
Integrated flushing valve

Further information:

Dual displacement motor A10VEC for track and wheel drives Size 45

Fixed displacement motor A10FSM Size 18

Fixed displacement motor A10FM RE 91 172 Size 23 - 63

Features

2

3

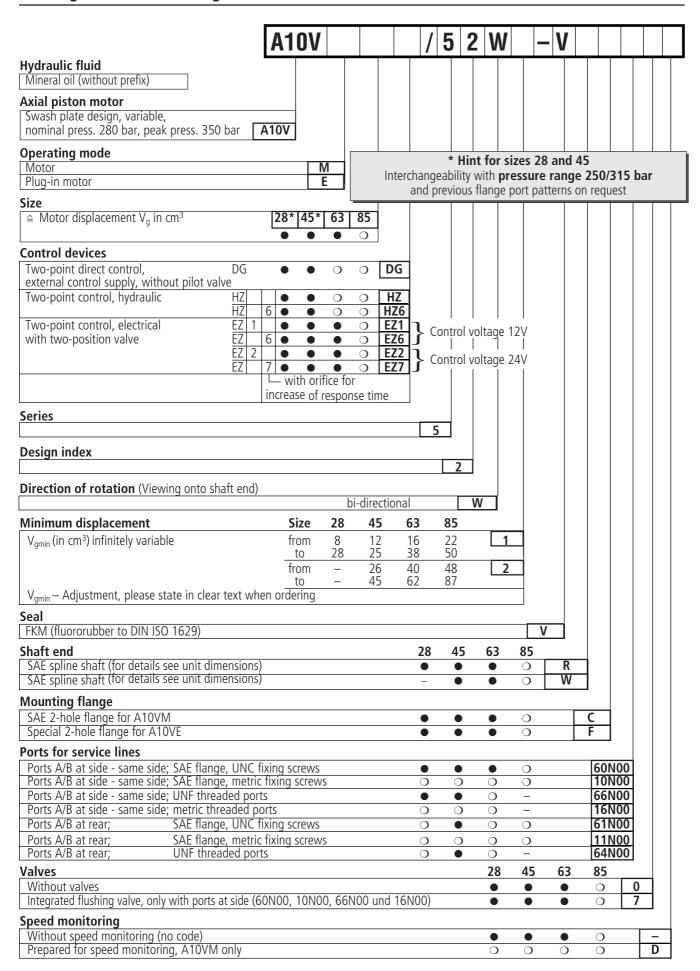
4

14

16

- Dual displacement motor, axial piston in swashplate design for hydrostatic transmissions in open and closed circuit applications
- Output speed directly proportional to the inlet flow and inversely proportional to the motor displacement
- Output torque increases proportional to the pressure
 difference between high and low-pressure sides and increasing displacement
- Heavy-duty bearings for long service life
- 10 High permissible output speed
- Well proven A10 rotary unit technology
- 12 High power/weight ratio compact size
- 13 Cost effective
 - Low noise
- Control range 1 : 3.75
 - External direct control supply possible
 - Minimum displacement can be set externally
 - SAE 2-bolt mounting flange on A10VM
 - Special 2-bolt flange on A10VE

Ordering code / standard range



= available

Technical data

Hydraulic fluid

For extensive information on the selection of fluids and for application conditions, please consult our data sheets RE 90220 (mineral oils) or RE 90221 (environmentally accetable hydraulic fluids).

You might have to consider reduced operating data with environmentally accetable hydraulic fluids. Please contact our technical department (please indicate type of the hydraulic fluid used for your application on the order sheet).

Operating viscosity range

In order to obtain optimum efficiency and service life, we recommend that the operating viscosity (at operating temperature) be selected from within the range:

$$v_{opt} = opt.$$
 operating viscosity 16...36 mm²/s

referred to the circuit temperature (closed circuit) or tank temperature (open circuit).

Viscosity limits

The limiting values for viscosity are as follows:

$$v_{min} = 5 \text{ mm}^2/\text{s}$$

short term at a max. permissible temperature of $t_{max} = 115$ °C.

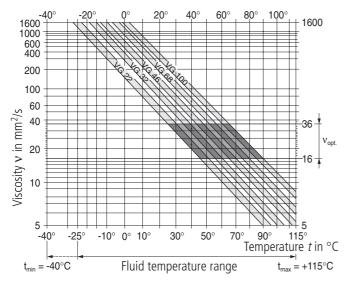
Please note that the maximum fluid temperature must also not exceed 115 °C in certain areas (e.g. bearing area).

$$v_{max} = 1600 \text{ mm}^2/\text{s}$$

short term on cold start ($t_{min} = -40 \, ^{\circ}$ C).

Special precautions are required at temperatures between -25 $^{\circ}$ C and -40 $^{\circ}$ C, depending on the installation conditions. Please consult our technical department.

Selection diagram



Notes on the selecting of the hydraulic fluid

In order to select the correct fluid, it is necessary to know the operating temperature in the loop (closed circuit) or the tank temperature (open circuit) in relation to the the ambient temperature.

The hydraulic fluid should be selected so that within the operating temperature range, the operating viscosity lies within the optimum range (v_{opt}) (see shaded section of the selection diagram). We recommend that the highest possible viscosity range should be choosen in each case.

Example: At an ambient temperature of X °C the operating temperature (closed circuit: loop temperature; open circuit: tank temperature) is 60°C. Within the operating viscosity range (v_{opt}) shaded area), this corresponds to viscosity ranges VG 46 or VG 68; VG 68 should be selected.

Important: The leakage oil (case drain oil) temperature is influenced by pressure and motor speed and is always higher than the circuit or tank temperature. However, at no point in the circuit may the temperature exceed 115 °C.

If it is not possible to comply with the above conditions because of extreme operating parameters or high ambient temperatures please consult us.

Filtration of fluid

The finer the filtration the better the achieved cleanliness of the pressure fluid and the longer the life of the axial piston unit.

To ensure the functioning of the axial piston unit a minimum cleanliness of: 9 to NAS 1638

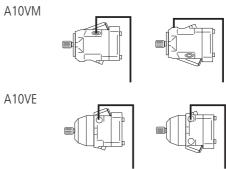
18/15 to ISO/DIS 4406.

Please consult us, if it is not possible to comply with the above conditions.

Mounting position

Any. The motor housing must be filled with hydraulic fluid when starting up and during operation. The leakage fluid line must be routed so that the housing is not drained when the motor stops. The end of the line must enter the tank below the minimum oil level.

The highest leakage oil port must be used in all installation positions to fill the housing and to connect the drain line.



Please consult Brueninghaus Hydromatik if the motor is to be installed vertically.

Technical data

Operating pressure range

Pressure at port A or B

(Pressure data to DIN 24312)

Sum of the pressure at ports A and B must not exceed 560 bar.

Case drain pressure

Maximum permissible case pressure at ports L and L₁

P_{abs max} _____ 2 bar abs.

Direction of rotation

Flow B to A = Right-hand rotation Flow A to B = Left-hand rotation

Displacement

The minimum displacement steplessly adjustable within the range of the screw lengths 1 or 2 (see model code page 2).

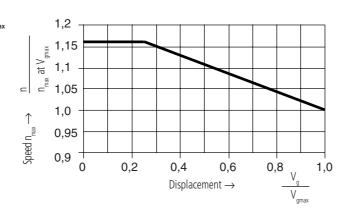
Please state min. displacement in clear text when ordering; it will be factory set.

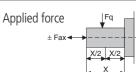
Table of values (theoretical values, ignoring η_{mh} and η_{v} : values rounded)

Size					28	45	63	85
Motor displacement			V _{g max}	cm ³	28	45	62	87
			V _{g min}	cm ³	8	12	16	22
Max. speed ¹)	at V _{g max}		n _{max}	rpm	4700	4000	3300	3100
	at V _{g min}		n _{max}	rpm	5300	4600	3800	3500
Max. inlet flow	at n_{max} and $V_{g max}$		$q_{v max}$	L/min	131.6	180	205	270
Max. output power	at n_{max} and $V_{g max}$	$\Delta p = 280 \text{ bar}$	P_{max}	kW	61	84	95	125
Max. torque	at V _{g max}	$\Delta p = 280 \text{ bar}$	T_{max}	Nm	125	200	276	387
Mass moment of inertia (about the output shaft)			J	kgm ²	0.0017	0.0033	0.0056	0,0167
Filling volume, approx.				L	0.6	0.7	0.8	1
Weight, approx.			т	kg	14	18	26	34
Permissible load on output shaft, max. perm. axial force			F _{ax max}	N	1000	1500	2000	3000
Max. perm. radial force			F _{q max}	N	1200	1500	1700	2000
Actual starting toque at $n = 0$ rpm $\Delta p = 280$ bar		•	Nm(app	rox.) 92	149	205	253	

1) At max. speed the low pressure must see at least 18 bar.

Determination of n $_{max}$





Calculating size

Inlet flow
$$q_v = \frac{V_g \bullet n}{1000 \bullet n_v}$$
 [L/min] $V_g = \text{geometric motor displacement per revolution [cm³]}$ $\Delta p = \text{pressure differential [bar]}$

Torque
$$T = \frac{1.59 \cdot V_g \cdot \Delta p \cdot \eta_{mh}}{100}$$
 [Nm] $n = \text{speed [rpm]}$ $\eta_v = \text{volumetric efficiency}$

Output power
$$P = \frac{T \bullet n}{9549} = \frac{q_v \bullet \Delta p \bullet \eta_t}{600}$$
 [kW] $\eta_{th} = \text{mechanical-hydraulic efficiency}$ $\eta_{th} = \text{total efficiency}$ $\eta_{th} = \text{mechanical-hydraulic efficiency}$

Output speed
$$n = \frac{q_v \bullet 1000 \bullet \eta_v}{V_g}$$
 [rpm]

Direct control pressure DG

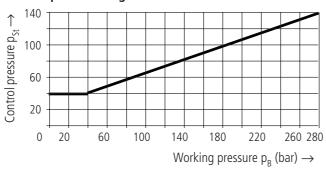
Normally, the motor is at max. displacement. By applying an external pressure to port G, the destroking piston is directly pressurized and the motor switches to minimum displacement.

The minimum required control pressure is $p_{st} \ge 40$ bar.

This control pressure depends directly on the working pressure \boldsymbol{p}_{B} in port A or B.

See control pressure diagram below. With a control pressure above this minimum required pressure level the motor will destroke properly.

Control pressure diagram



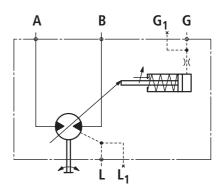
Control pressure = 0 bar $\stackrel{\triangle}{=} V_{g \text{ max}}$

Control pressure \geq 40 bar $\stackrel{\triangle}{=}$ $V_{q min}$ (see control pressure diagram)

The maximum permissible control pressure $p_{st} = 280$ bar.

 $\rm V_{\rm g\;min}$ - setting, please state in clear text when ordering.

Circuit diagram



Ports

A,B Pressure ports

L, L₁ Drain ports

G, G₁ External control pressure ports

Hydraulic two-point control HZ / HZ6

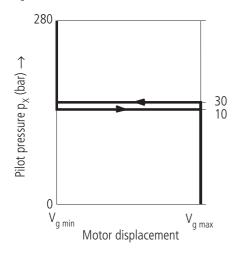
Normally, the motor is at max. displacement. By applying a pilot pressure p_X to port X ($p_X \ge 30$ bar), the destroking piston is pressurized and the motor switches to minimum displacement.

The necessary control pressure is via a shuttle valve, taken out of the port A or B.

A minimum operating pressure difference of $\Delta p_{A,B} \ge 20$ bar is required.

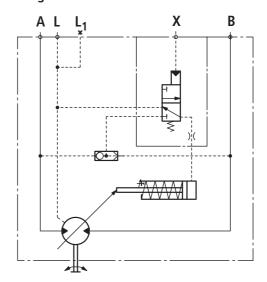
Only max. and min. displacements are possible.

 $V_{q \, min}$ - setting, please state in clear text when ordering.



Pilot pressure $p_X = 0$ bar $\triangle V_{g \text{ max}}$ Pilot pressure $p_X \ge 30$ bar $\triangle V_{g \text{ min}}$

Circuit diagram HZ



Ports

A,B Pressure ports

L, L₁ Drain ports

X Pilot pressure port

Technical data HZ / HZ6

Minimum pilot pressure	30 bar
Max. permissible pilot pressure	280 bar

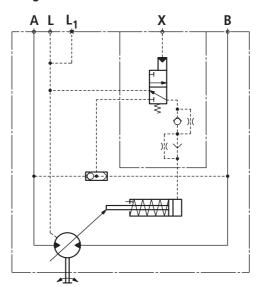
Control HZ6 with shuttle orifice to increase swivel time

Slow down of swivel action by means of shuttle orifice.

This enables a smooth swivel action.

Standard shuttle orifice size = 0.21 mm; other sizes on request.

Circuit diagram HZ6



Ports

A,B Pressure ports

L, L₁ Drain ports

X Pilot pressure port

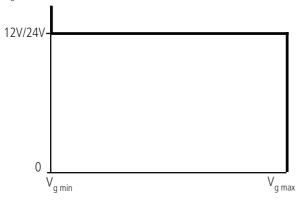
Electrical two-point control EZ.

Normally, the motor is at max. displacement. By energizing the solenoid of the control valve, the destroking piston is pressured, and the motor switches to minimum displacement.

The necessary control pressure is via a shuttle valve, taken out of the port A or B.

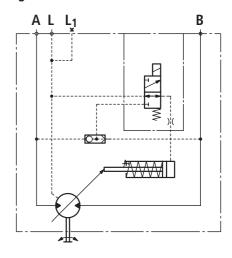
A minimum operating pressure difference of $\Delta p_{A,B} \ge 20$ bar is required. Only max. and min. displacements are possible.

 $\rm V_{g\,min}$ - setting, please state in clear text when ordering.



 $\begin{array}{ll} \text{De-energized} & \qquad & \triangleq \text{V}_{\text{g max}} \\ \text{Energized} & \qquad & \triangleq \text{V}_{\text{g min}} \end{array}$

Circuit diagram EZ1/2



Ports

A,B Pressure ports
L, L₁ Drain ports

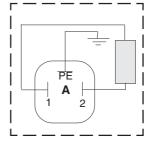
Technical data EZ.

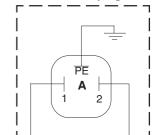
Type	EZ1/6	EZ2/7
Supply voltage (DC)	12 V	24 V
Power consumption	26 W	26 W
Duty cycle	100%	100%
Type of protection	IP 65	IP 65

Features:

- With spring return
- Solenoid plug can be turned 4 x 90°

Connection to solenoid





Connection to plug

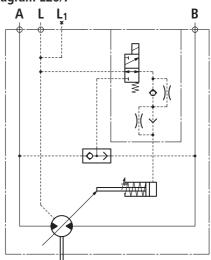
Control EZ6/7 with shuttle orifice to increase swivel time

Slow down of swivel action by means of shuttle orifice.

This enables a smooth swivel action.

Standard shuttle orifice size = 0.21 mm; other sizes on request.

Circuit diagram EZ6/7



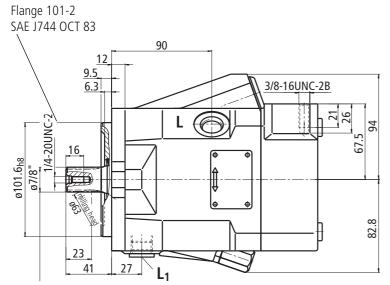
Ports

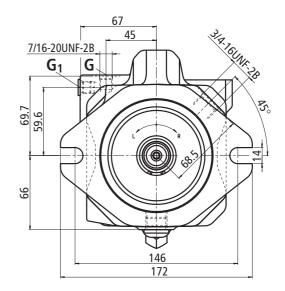
A,B Pressure ports

L, L₁ Drain ports

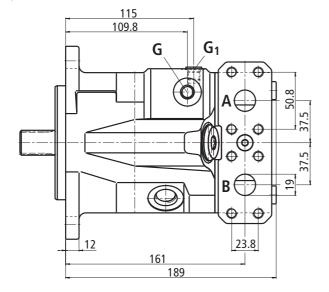
Two-point direct control DG port plate 60

Before finalising your design, please request certified assembly drawing.





Shaft **R** 22-4; SAE J744 OCT 83 7/8" dia. splined shaft; 30° pressure angle; 13 teeth; 16/32 pitch; flat base; flank centering; fit class 5; ANSI B92. 1a-1976



Ports

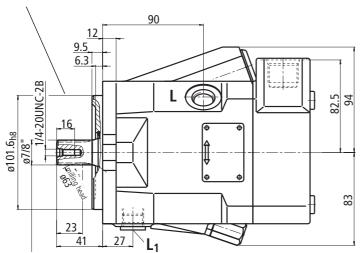
A,B Pressure ports SAE flange 3/4 ", high-pressure series (code 62)

L, L₁ Drain ports 3/4 - 16 UNF - 2B (L₁ plugged) G, G₁ External control pressure ports 7/16 - 20 UNF - 2B (G₁ plugged)

Two-point hydraulic control HZ port plate 66

Before finalising your design, please request certified assembly drawing.

Flange 101-2 SAE J744 OCT 83

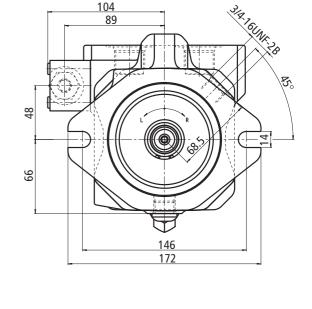


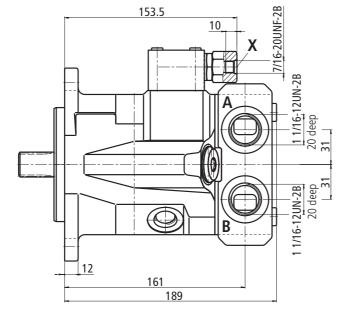
Shaft R 22-4; SAE J744 OCT 83

7/8" dia. splined shaft; 30° pressure angle; 13 teeth;

16/32 pitch; flat base; flank centering;

fit class 5; ANSI B92. 1a-1976





Ports

A, B Pressure ports Threaded O-ring boss 1 1/16-12UN-2B

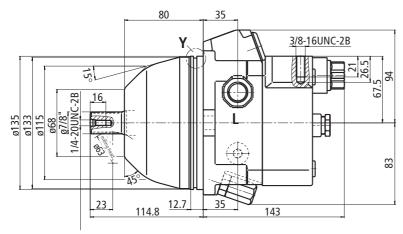
 L, L_1 Drain ports 3/4 - 16 UNF - 2B (L_1 plugged)

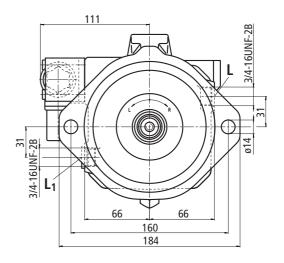
X Pilot pressure port

7/16 - 20 UNF - 2B

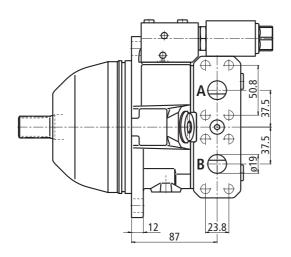
Two-point electrical control EZ. with two-position valve, port plate 60

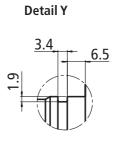
Before finalising your design, please request certified assembly drawing.





Shaft **R** 22-4; SAE J744 OCT 83 7/8" dia. splined shaft; 30° pressure angle; 13 teeth; 16/32 pitch; flat base; flank centering; fit class 5; ANSI B92. 1a-1976





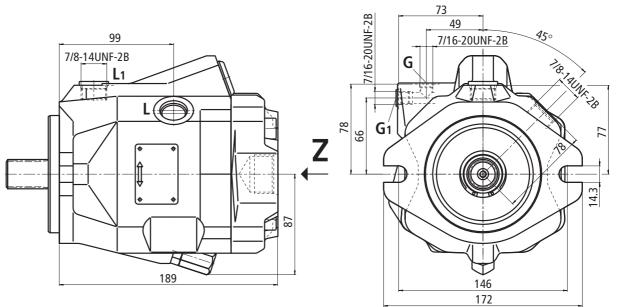
Ports

A,B Pressure ports SAE flange 3/4 ", high-pressure series (code 62)

L, L_1 Drain ports 3/4 - 16 UNF - 2B (L_1 plugged)

Two-point control, direct control pressure DG, port plate 64

Before finalising your design, please request certified assembly drawing.

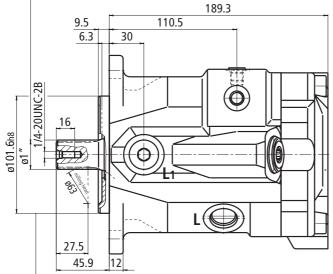


Shaft R 25-4; SAE J744 OCT 83

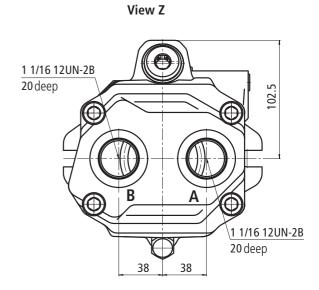
1" dia. splined shaft; 30° pressure angle; 15 teeth;

16/32 pitch; flat base; flank centering;

fit class 5; ANSI B92. 1a-1976



Flange 101-2 SAE J744 OCT 83



Shaft **W** see page 12.

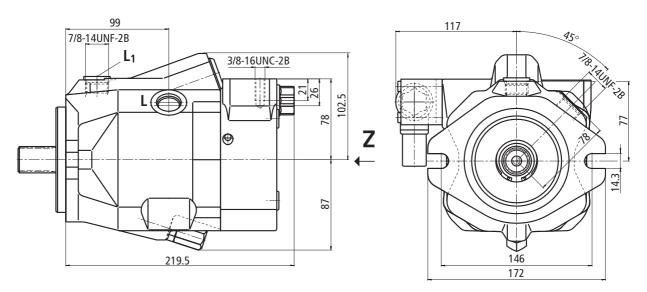
Ports

A,B Pressure ports Threaded O-ring boss 1 1/16 12UN-2B

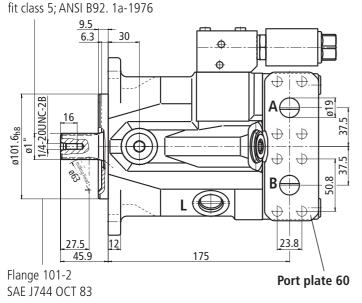
 L, L_1 Drain ports 7/8-14UNF-2B (L_1 plugged) G, G1 External control pressure ports 7/16-20UNF-2B (G_1 plugged)

Two-point electrical control EZ. with two-position valve, port plate 60 and 61

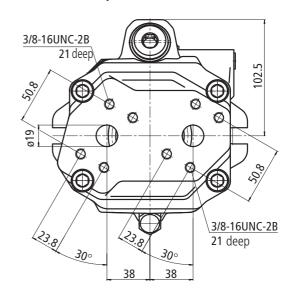
Before finalising your design, please request certified assembly drawing.

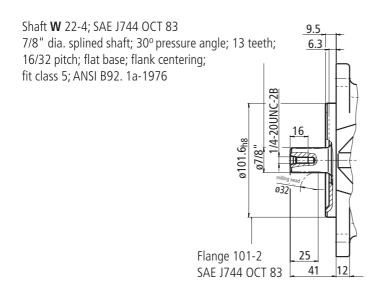


Shaft **R** 25-4; SAE J744 OCT 83 1" dia. splined shaft; 30° pressure angle; 15 teeth; 16/32 pitch; flat base; flank centering;



Port plate 61, View Z





Ports

A,B Pressure ports SAE flange 3/4 ",

high-pressure series (code 62)

L, L₁ Drain ports 7/8-14UNF-2B (L₁ plugged)